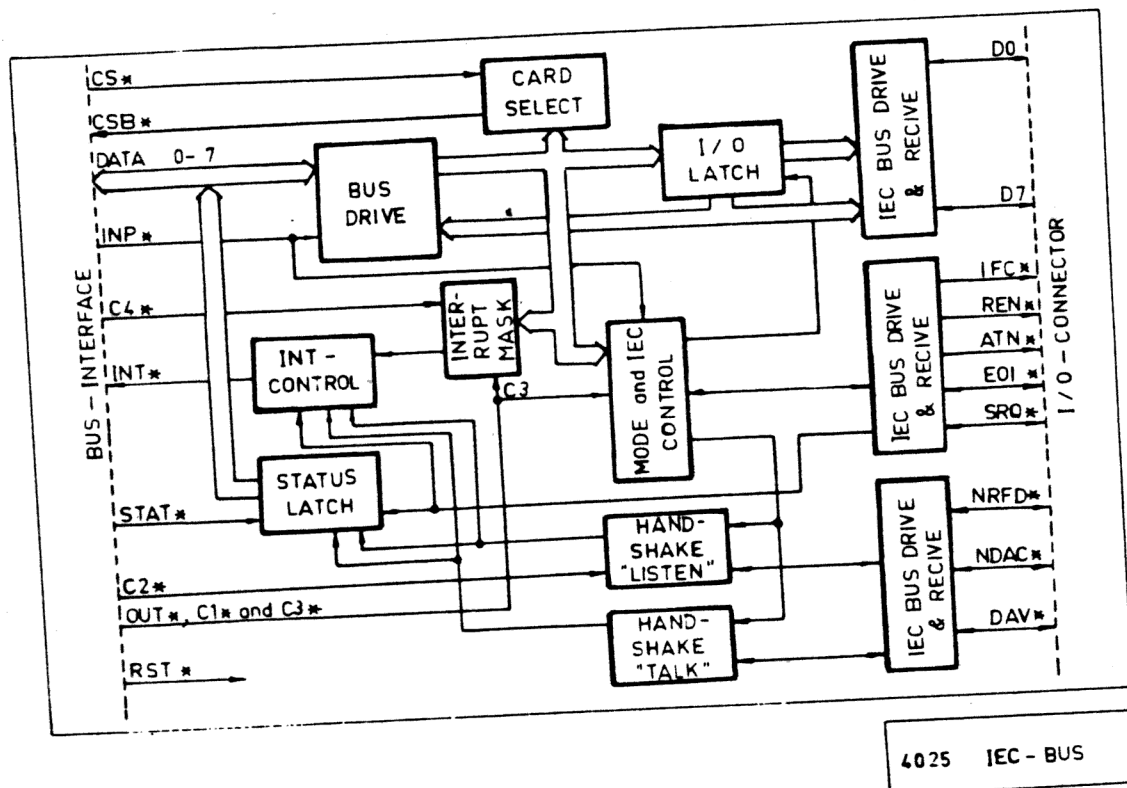


OKT 79	1	4	X
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4025 provides DATABOARD 4680 users interfacing to the IEC-bus.

It conforms fully to the specification with respect to the three basic functional elements:

- 1) listener
- 2) talker
- 3) controller

These basic functions are defined as subsets C1, C2, C3, C4 and C25 of the standard. 4025 acts as the supreme controller of the connected IEC-bus.

- C1= System Controller
- C2= Send IFC and Take Charge
- C3= Send REN
- C4= Respond to SRQ
- C25= Send I.F. Messages
Parallel Poll
Take Control Synchronously

Software Support is available through options in Extended Basic and Basic for ABC 80.



SPECIFICATION

Power supply	+5V \pm 5 % 500 mA
Peripheral interface	Conforms fully to the specification IEC 66.22 of the "IEC-bus".
Connectors	B 64 pin two-row Europe connector on the bus as well as on the I/O sides.
Bus connection	On the I/O side of the 4680-bus, provides the signal CSB ^X for use at bus expansion.
Size	Standard Europe card 100 x 160 mm.

JUMPERS

None

CARD SELECT

Is done by code plug – position 2B on board.
See System Manual about the coding. Standard = 61Q(031H).

COMMANDS

INP DATA	Reads 8 bits received data. Data is valid only when statusbit 7 is active.
INP STAT	Reads status. The bits have the following significance:
D0	not used
D1	not used
D2	NRFD (Not Ready For Data). Active 0.
D3	NDAC (Not Data Accepted). Active 0.
D4	EOI (End Or Identify). Active 0.
D5	SRQ (Service ReQuest). Active 0.
D6	Data accepted ("talk"-mode). Active 0.
D7	Data valid ("listen"-mode). Active 0.
OUT DATA	Output 8 bits of data for transmission. The command is allowed only in "talk"-mode.
OUT C1	Controls mode of activity and control-signalling. The data-byte is used in the following way: D0 - D2 = Address D7 Controls the state of the concerned function: D7 = 0 = Reset D7 = 1 = Set

Address

0	Not IFC (InterFace Clear).
1	REN (Remote ENable).
2	EOI.
3	ATN.
4	"talk"-mode.
5	"listen"-mode.
6	"Not automatic ready" in "listen"-mode.
7	not used.

Note: "talk"- and "listen"-modes are not allowed to be active at the same time. If both are commanded actives the "talk"-mode is set up.

OUT C2	Controls the handshake in "listen"-mode when "Not automatic ready" is activated. Next transfer will follow.
OUT C3	Clear interface. Has the same function as RST-command but is controlled by the cardselection.
OUT C4	Selective INTERRUPT ENABLE. The data-byte is evaluated as follows:
D0	not used
D1	not used
D2	not used
D3	not used
D4	= 1, interruptsignal if EOI is active.
D5	= 1, interruptsignal if SRQ is active.
D6	= 1, interruptsignal if "Data accepted" is active ("talk"-mode).
D7	= 1, interruptsignal if "Data valid" is active ("listen"-mode).

IEC-CABLE, PRODUCT NUMBER 7225

A special adaptor cable is supplied. It connects to 4025 and provides a standard IEC-bus connector (Amphenol 17-20250) ready to connect to the first instrument to be interfaced. Other equipment is connected in daisy-chain.

Length = 2 m.

The following table shows the interchange between IEC-cable and 4025 I/O-connector.

The colour-code is the same as specified for the Philips IEC-cable.

IEC

1	white	
2		green
3	gray	
4		blue
5	white/brown	
6		grey/rose
7	white/green	
8		white/yellow
9	- white/grey	
10		white/orange
11	white/blue	
12		white/red
13	screen	
14		brown

4025 (DIN 41612)

3B	D0*
4B	D1*
5B	D2*
6B	D3*
7B	REN*
8B	EOI*
9B	DAV*
10B	NRFD*
11B	NDAC*
12B	IFC*
13B	SRQ*
14B	ATN*
15B	
16B	D4*

Contd. IEC

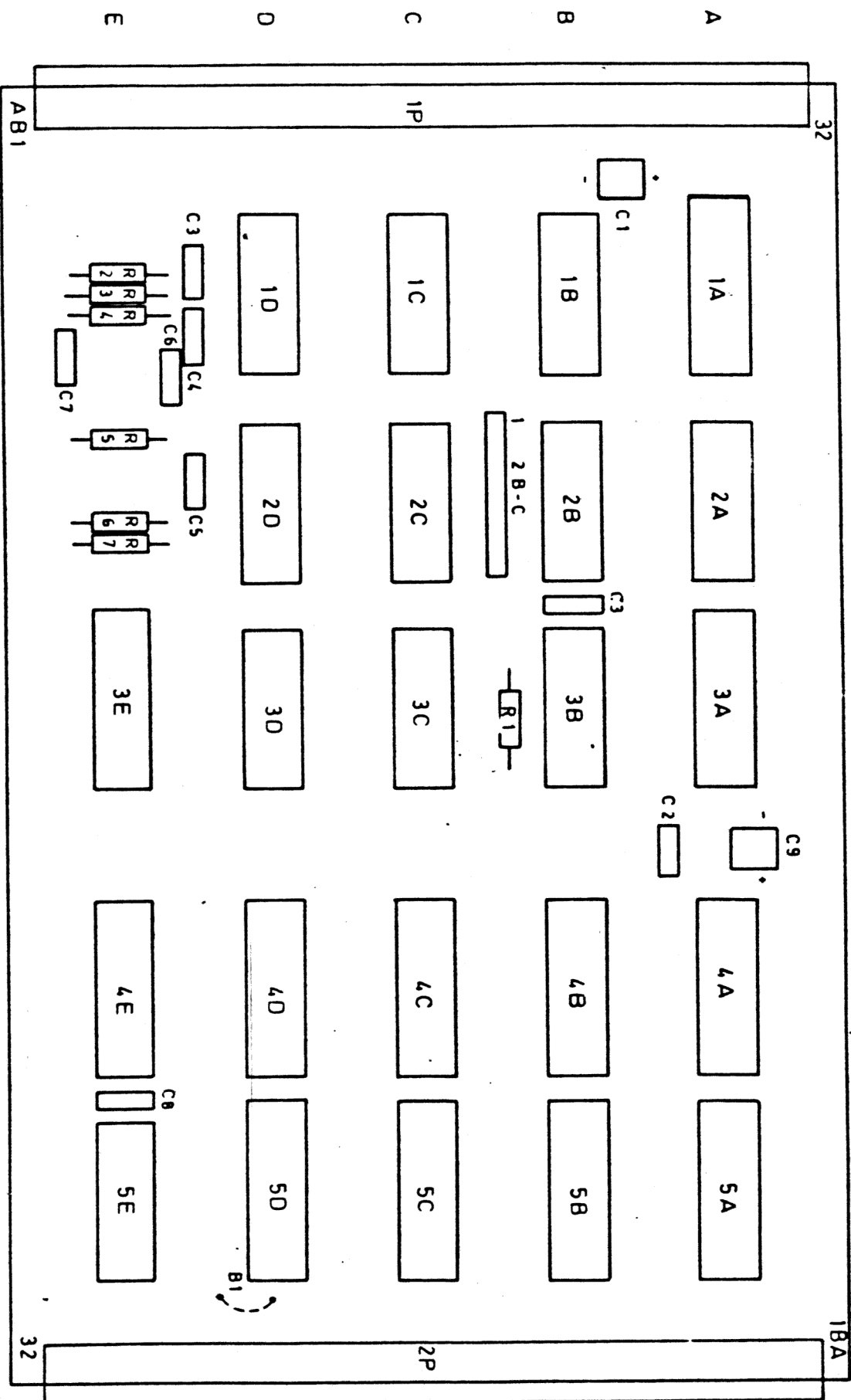
4025 (DIN 41612)

15	yellow		17B	D5*
16		rose	18B	D6*
17	red		19B	D7*
18		yellow/green	7A	
19	blue/red		8A	
20		brown/green	9A	
21	yellow/brown		10A	
22		grey/brown	11A	
23	rose/brown		12A	
24		brown/blue	13A	
25	brown/red		14A	

REFERENCES

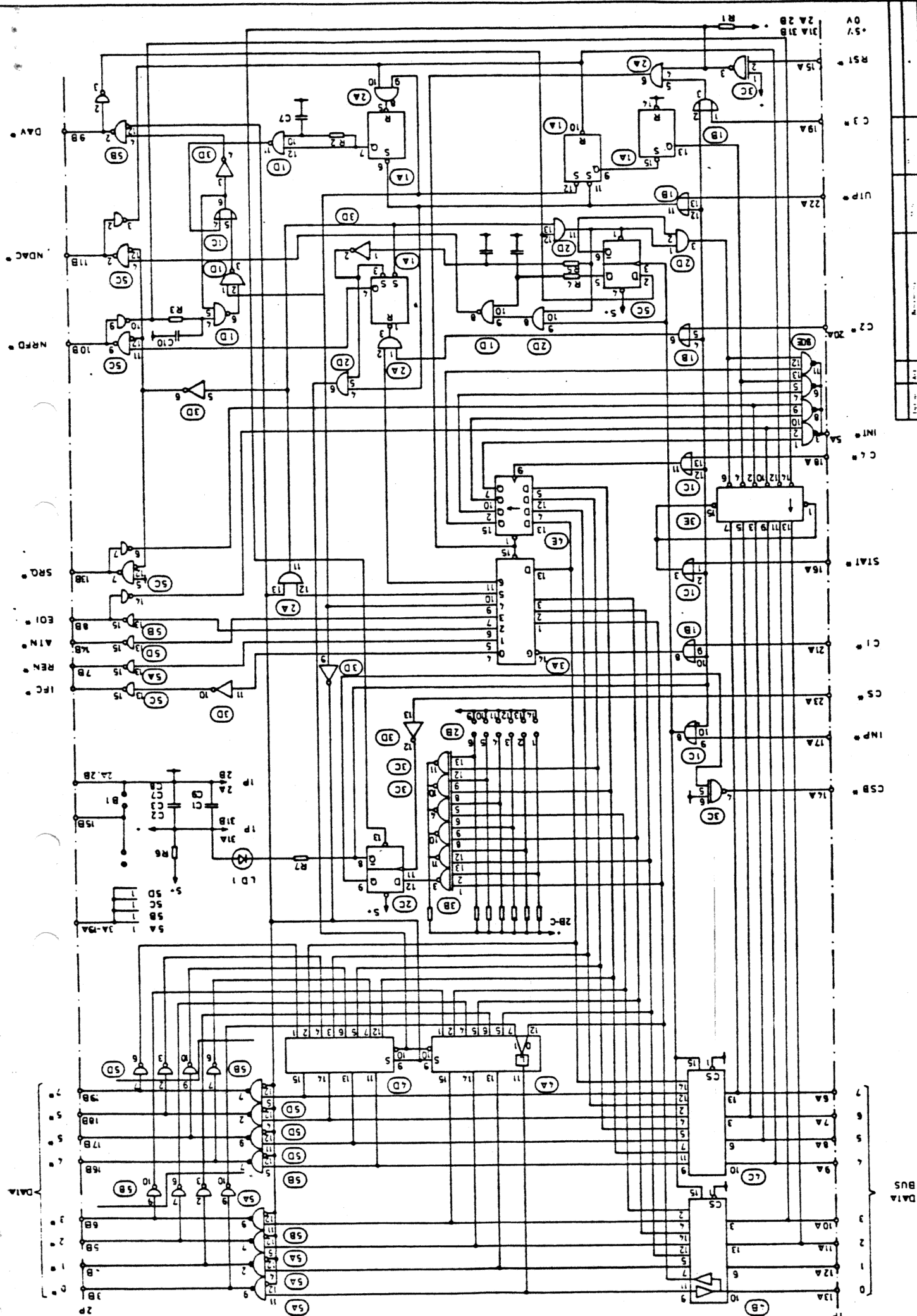
IEEE Standard Digital Interface for Programmable Instrumentation.
IEEE Standard 488 - 1975.

Datorteknik "Datoranvändning med IEC-buss" Sune Windisch,
Liberförlaget (lärobok för användning av 4025 genom IEC-optionerna
i Basic).



COMMENT: 2B = CODE PLUG FOR CHANNEL SELECTION.
JUMPER B1 NOT INSTALLED = SHIELD NOT CONNECTED TO 4680 SYSTEM 0V.

	C	REV NR	DATAINDU	7IER AB	1, INTERFACE	82-4025-00
7903	DATUM	TABY	SWEDEN			



The IEC-bus is a standard approach to interconnect instrumentation. It is issued by "International Electro-Technical Committee" as specification IEC 66.22. It was published 1975 as ANSI-Standard IEEE 488, IEEE Standard Digital Interface for Programmable Instrumentation.

The IEC-bus interfaces to DataBoard 4680 through the I/O-module 4025. It provides a simple means of interfacing instrumentation equipment to a DataBoard 4680 computer and as well ABC 80(expanded with DataBoard 4680 expansion chassis as Datadisk 80).

The DataBoard 4680 IEC-bus interface packet comprises:

- I/O interface module, prod. No. 4025
- IEC cable, prod. No. 7225
- Software support in Basic
 - a) Option in Extended Basic
 - b) PROMed program driver for ABC 80/Datadisk 80 application.

Cable and Interface module are described by datasheet 4025.

The above program drivers offer through Basic users a quick availability to the technique of handling the IEC-bus in programming. This document describes how to use these IEC-options. Direct control of 4025 is still available and, if faster data transfers are required, is controlled by an Assembler program. Data sheet 4025 provides the complete list and description of the I/O-commands.

The next sections describe:

- IEC OPTION
 - Details and how to use the optional program driver for Basic
- IEC BUS SPEC - 4025
 - Describes the standard of IEC bus as applied to 4025.

Tables and figures are located in the end. The Remote Message coding as the 7-bit ISO-code is given.



IEC-OPTION

Specification

Program driver: Option in Extended Basic
Volume = 1 K

PROMed program driver for ABC 80/Datadisk 80 applications:
Volume = 1K (2708)
Mem. allocation: On the DOS PROM-module
(1:st mem. circuit on the second row)

Channel address: Standard 61_8 (49_{10})

Interrupt-driven: No

Controller
Talker Address: "U"

Controller
Listener Address: "5"

Not supported functions of 4025:

Automatic Ready (OUT C1) (requires interrupt handling)

Parallel Poll (SRQ) (available through direct
I/O-commanding.

General

The user programming is naturally dependent on the instrumentation equipment connected. Each instrumentation is specified by a manual with respect to the use in an IEC-bus configuration. The basic action to be made is selection of the device address which normally is done by jumpers.

The user programming requires following steps:

- 1) Connect the user program to the IEC-option known to the system as "IEC:".
See "OPEN- and CLOSE statements".
- 2) Commanding data transfer on the IEC-bus.
See "Commanding".
- 3) Handling received data.
See "IEC\$"
- 4) Disconnection of the user program from the IEC-option. Makes the IEC-bus free for another user (essential in Multi-user Basic).
See OPEN- and CLOSE-statements.

The user has, however, not access to all functions so we describe the "Restrictions" and how to handle them.

OPEN- and CLOSE-statements

OPEN issues	IFC	(Interface clear) false signal
	REN	(Remote enable) true signal
CLOSE issues	IFC	Signal true
	REN	Signal false

Format is shown by the following:

```
10  OPEN "IEC:"  AS FILE 31

100 CMD "U6"... } Body of the user program

999 CLOSE 31
```

The channel number is not significant. OPEN and CLOSE are necessary for initialization of the IEC-bus.

Commanding

Format: [statement number] CMD [A1\$], C1\$, A2\$, C2\$,...

Where: A1\$;A2\$ etc

are string expressions which define the TALKER(s) and LISTENER(s). Each string character defines a device address. The first parameter (A1\$) is optional as talker(s) and listener(s) can be the same as commanded before. The ATN signal on the IEC-bus is sent true.

C1\$,C2\$ etc are string expressions, character by character, to control the device(s) connected to the IEC-bus.

The ATN signal is sent false.

The parameter delimiter", "switches the IEC- option from one mode to the other, that is the ATN message from true to false etc.

Example 1: 100 CMD "?U1","BCD1F2A"

Where:

"?U1" corresponds to A1\$

"BCD1F2A" corresponds to C1\$

"?" = UNL (unlisten), refer to table 3, which resets all listener
"u" defines the new talker (=controller) and "1" defines the new listener.

"BCD1F2A" contain commands to the listener as specified for the specific instrument.

Example 2: 110 CMD "?U1" +CHR\$(8)

Where: CHR\$(8) adds the string value [8] (=backspace) as the last character of the address-string. The function CHR\$ gives us a way to handle non-attributed codes.

Talker(s) require no reset, refer to table 3. In this case the 4025 ("U") is specified as talker. Any talker will automatically be reset as only one talker at a time is allowed.

The listener has the address "1".

Note: Talker- and listeneraddresses are allowed in opposite order.

IEC\$

The function IEC\$(arg) provides the user the received data.

Example: 110 OPEN "IEC:" AS FILE 35
120 CMD "?U7"+CHR\$(8)
130 CMD "?5R"
140 PRINT IEC\$(13)
150 GOTO 120

Line 130 commands the 4025 as listener and an instrument as talker. The received information (13 characters) is then transferred at line 140:- from the buffer of the IEC-option to the program by using the function IEC\$.

Format: IEC\$(<arg>)

Where: <arg> is limited only by memory-space available. The IEC-option reads the number of characters that is specified by the argument.

Restrictions

SRQ (service request) is not implemented in the IEC-option. The user has to solve this signalling which concerns PP (parallel Poll) by explicit I/O-commanding of the 4025.

As stated before, "automatic ready" is not used. This is significant when using the 4025 by I/O-interrupt-signal.

Messages

A remote message is sent or received by the interface via one or several of the signal lines.

A message derived from or sent as state of one line is referred to as uniline message (U) and if two or more lines are used, then the message is referred to as multiline message (M).

A uniline message is valid as soon as its corresponding state is detected.

A multiline message is valid within the context of SH (STRS - Source TRansfer State) and AH (ACDS - ACcept Data State) functions.

Note: AH = Acceptor Handshake
 SH = Source Handshake

Interface Messages

Each interface message is sent to cause a state transition within another interface. The interface messages are sent when the ATN message is true. The message coding is defined in table 3 and corresponds to ISO-7 bit code.

Device Dependent Messages

After a talker and listener(s) have been addressed via interface messages, any common binary, BCD or alphanumeric code may be used when the ATN message is false.

Remote Message Coding

Table 2)) shows the coding of each remote specific message as sent by one source.

The conventions and the symbols used in the table are specified as follows:

Ø = logical zero
1 = logical one
x = "don't care" for receive
x = "must not drive" for send

Level assignments:

Ø = high state signal level
1 = low state signal level

Symbols:

U = Uniline message
M = Multiline message
AC = Addressed Command
AD = ADress - talk or listen
DD = Device Dependent
HS = HandShake
UC = Universal Command
SE = SEcondary
ST = SStatus

Notes:

- 1) D1 - D8, databits
- 2) E1 - E8, code for EOS message
- 3) L1 - L5, listen address
- 4) T1 - T5, talk address
- 5) S1 - S5, secondary address
- 6) S, specifies the sense of PPR
P1 - P3, specify the PPR message in parallel poll
- 7) D1 - D4, specify bits that must be sent all zeros
but do not need to be decoded
- 8) S1 - S6, specify the device dependent status. Databit
S8 6 is used for the RQS message.
- 9) If LACS is inactive, the true message value must be ignored
- 10) If ATN is false, the true message value must be ignored
- 11) IDY message is sent true only when ATN is true.
- 12) END message is sent true when ATN is false.

State Diagrams

The controller functions are graphically described by state diagrams. The handshake signalling is not presented as it is implemented in hardware. The controller, as referred to in the text, shall be considered as a compound function of the user program driver and the 4025 itself. The controller states shall be treated as software states. Some of the states are of no significance to the software control. They are nevertheless shown for reference to the specification of the general standard. The handshake signalling is a dynamic sequence of hardware states on the INP DATA and OUT DATA commands with the overlaying controller states.

The diagrams are described with a short description of every state. The terms "true" and "false" are assumed to mean the guaranteed value received. Passive true and false terms mean that the values are not guaranteed to be received and that they are allowed to be overread.

The diagrams use the following conventions:

A local message (a program control of 4025) is represented by a three-letters mnemonic written in lower case.

A remote message is represented by a three-letters mnemonic written in upper case.

A linkage to other state diagrams is represented by a four-letters mnemonic enclosed as the following example to the LISTENER function, which stands for 'listener active state'.
(LACS)

The user will, however, by using the IEC-options not be interfered with the controller states, that is I/O-commanding 4025.

Talk (T) and listen (L) functions

4025 is provided with the capability to act either as a talker, as a listener or as a passive listener on the bus. These functions correspond to complementary functions of the devices. The ATN message is false When the conversation partner(s) are chosen, 4025 is set to the concerned mode with the C1 command.

Option for automatic ready-signalling in listen-mode is provided. The ready signal is executed with the C2 command. EOI, used by a bi-directional slave, is provided as interrupt and status.

Service Request (S R)

The SR function provides a device with the capability to asynchronously request service from the controller. "Service request" is provided as interrupt and status.

Parallel Poll (P P)

The PP function is used by the controller to periodically conduct a parallel poll of device service requests. Each of the devices can be assigned their own statusbit on the data bus. This allows eight devices, although any number can be handled through sharing data lines.

Controller (C) Function

The C function provides the capability to send device addresses, universal commands and addressed commands to devices over the interface. It provides also the capability to conduct parallel polls to determine which device(s) require service. These capabilities are exercised only when it is sending the ATN message.

The state diagrams of figure 1) and table 1) specify the set of messages and states required to effect transitions from one active state to another. They present also the messages sent during each state.

The following table specifies the messages that must be sent and the interactions required while each state is active.

CONTROLLER STATE DESCRIPTION

CACS	(Controller Active State) The ATN message must be sent continuously true. The IDY message must be sent continuously false. While these conditions are met the multiline messages specified by the following table may be sent.
CPWS	(Controller Parallel poll Wait State) C conducts a parallel poll but waits for the data lines to settle. The ATN and IDY messages must be sent true.
CSBS	(Controller StandBy State) Allows two or more devices to participate in a conversation as TALKER and LISTENER (S). Device dependant messages are sent over the interface. The ATN must be sent false. The IDY message must be sent passive false.

CSWS (Controller Synchronous Wait State)
C is in the process of entering the CAWS but waits for a specified time to make sure that the current active talker recognizes the ATN message. The ATN message must be sent true. The IDY message must be sent active or passive false.

CAWS (Controller Active Wait State)
C waits for a period before CACS. This fact guarantees that the EOI line has settled. The ATN message must be sent true. The IDY message must be sent false.

CSRS (Controller Service Requested State)
Notifies that at least one device on the interface is requesting service. Does not provide remote message sending.

CSNS (Controller Service Not requested State)
Notifies that no device on the interface is requesting service. Does not provide remote message sending.

SNAS (System Control not Active State)
All system control capabilities are relinquished. Does not provide remote message sending.

SACS (System Control Active State)
C is allowed to exercise its system control capabilities (in SIIS and SRIS). Does not provide remote message sending.

SIIS (System control Interface clear Idle State)

SINS (System control Interface clear Not active State)
The IFC message is sent false.

SIAS (System control Interface clear Active State)
Clears the interface. All interface functions connected to the system must respond with a transfer to a known initial state. The IFC message must be sent true.

SRIS (System control Remote Idle State)
C has now remote enable capability. The C functions set up will remain unchanged.

SRNS (System control Remote enable Not active State)
C is not engaged in enabling remote operation of other devices over the interface.

SRAS (System control Remote enable Active State)
C is actively engaged in enabling remote operations of other devices over the interface. The REN message must be sent continuously true.

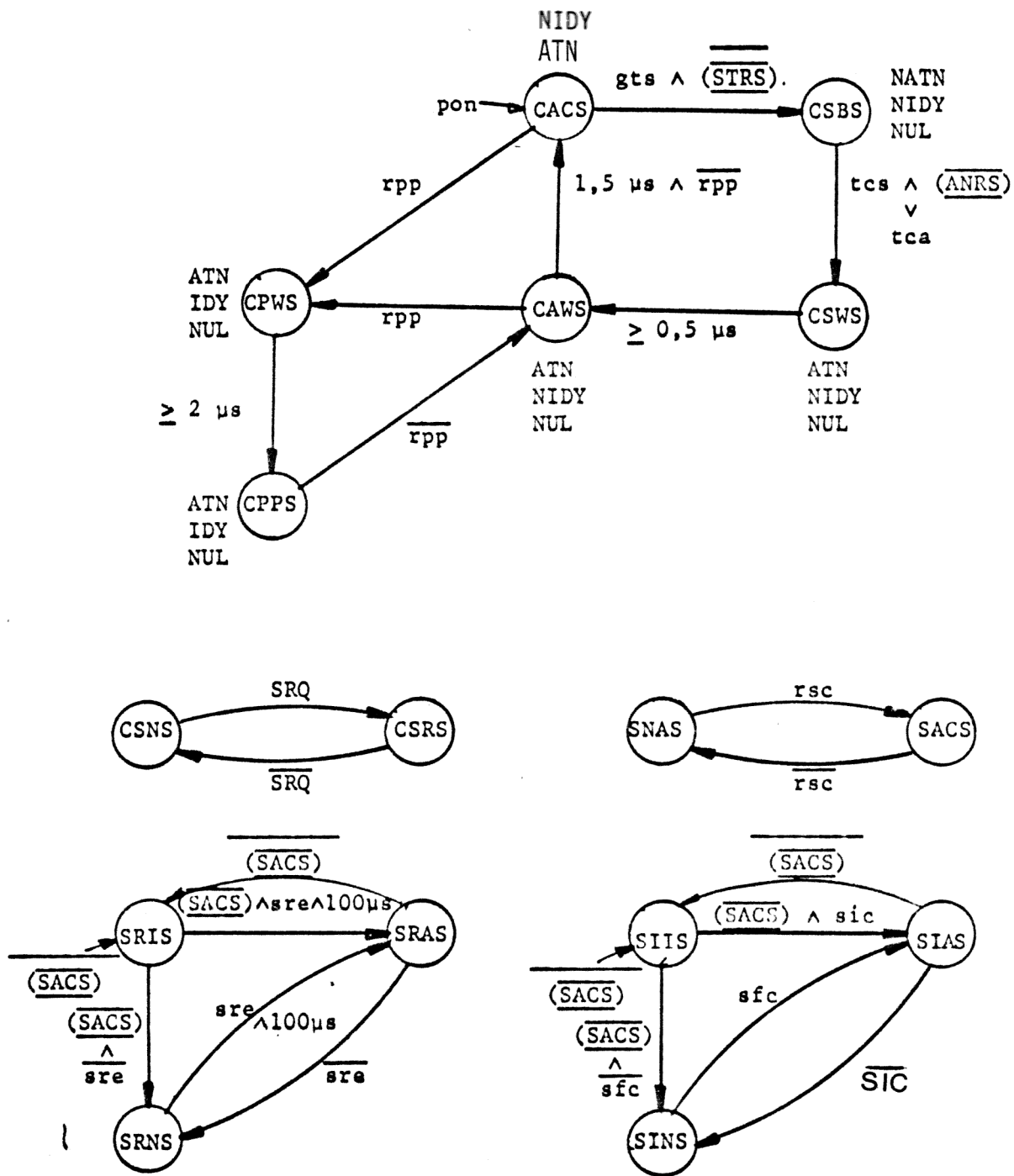


Figure 1. Controller State Diagram

TABLE 1

C M N E M O N I C S

pon = power on	CACS = controller active state
rsc = request system control	CPWS = controller parallell poll wait state
rpp = request parallell poll	CPPS = controller parallell poll state
gts = go to standby	CSBS = controller stanby state
tca = take control asyn- chronously	CAWS = controller active wait state
tcs = take control synchron- ously	CSWS = controller synchronous wait state
sic = send interface clear	CSRS = controller service requested state
sre = send remote enable	CSNS = controller service not requeste state
ATN = attention	SNAS = system control not active state
(<u>ANRS</u>) = acceptor not ready state (AH function)	SACS = system control active state
(<u>STRS</u>) = source transfer state (SH function)	SRIS = system control remote enable state
	SRNS = system control remote not active state
	SRAS = system control remote enable active state
	SIIS = system control interface clear idle state
	SINS = system control interface clear not active state
	SIAS = system control interface clear active state

TABLE 2

REMOTE MESSAGE CODING

		Bus signal line(s) and coding that asserts the true value of the message																		
MNEMONIC	MESSAGE NAME		T Y P E	C L A S S	D A T A	8	7	6	5	4	3	2	1	NN						
														VDC	N	I	Q	C		
																			DRD	A
															AFA	T	O	R	P	E
ACG	addressed com- mand group	(10)	M	AC	X	Ø	Ø	Ø	Ø	X	X	X	X	XXX	X	X	X	X	X	
ATN	attention		U	UC	X	X	X	X	X	X	X	X	X	XXX	1	X	X	X	X	
DAB	data byte	(1,9)	M	DD	D	D	D	D	D	D	D	D	D	XXX	X	X	X	X	X	
						8	7	6	5	4	3	2	1							
DAC	data accepted		U	HS	X	X	X	X	X	X	X	X	X	XXØ	X	X	X	X	X	
DAV	data valid		U	HS	X	X	X	X	X	X	X	X	X	1XX	X	X	X	X	X	
DCL	device clear	(10)	M	UC	X	Ø	Ø	1	Ø	1	Ø	Ø	Ø	XXX	X	X	X	X	X	
END	end	(9,11)	U	ST	X	X	X	X	X	X	X	X	X	XXX	X	1	X	X	X	
EOS	end of string	(2,9)	M	DD	E	E	E	E	E	E	E	E	E	XXX	X	X	X	X	X	
						8	7	6	5	4	3	2	1							
GET	group executive trigger	(10)	M	AC	X	Ø	Ø	Ø	Ø	1	Ø	Ø	Ø	XXX	X	X	X	X	X	
GTL	go to local	(10)	M	AC	X	Ø	Ø	Ø	Ø	Ø	Ø	Ø	1	XXX	X	X	X	X	X	
IDY	identify	(10,11)	U	UC	X	X	X	X	X	X	X	X	X	XXX	X	1	X	X	X	
IFC	interface clear		U	UC	X	X	X	X	X	X	X	X	X	XXX	X	X	X	1	X	
LAG	listen address group	(10)	M	AD	X	Ø	1	X	X	X	X	X	X	XXX	X	X	X	X	X	
LLO	local lock out	(10)	M	UC	X	Ø	Ø	1	Ø	Ø	Ø	Ø	1	XXX	X	X	X	X	X	
MLA	my listen address	(3,10)	M	AD	X	Ø	1	L	L	L	L	L	L	XXX	X	X	X	X	X	
								5	4	3	2	1								
MTA	my talk address	(4,10)	M	AD	X	1	Ø	T	T	T	T	T	T	XXX	X	X	X	X	X	
								5	4	3	2	1								
MSA	my secondary address	(5,10)	M	SE	X	1	1	S	S	S	S	S	S	XXX	X	X	X	X	X	
								5	4	3	2	1								
NUL	null byte		M	DD	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	XXX	X	X	X	X	X	
OSA	other secondary address	(10)	M	SE	(OSA = SCG ^ MSA)															
OTA	other talk address	(10)	M	AD	(OTA = TAG ^ MTA)															

TABLE 2, Continued

MNEMONIC	MESSAGE NAME			Bus singal line(s) and coding that asserts the true value of the message															
				T Y P E	C L S	D A S	8	7	6	5	4	3	2	1	NN				
															VDC	N	I	Q	C
PCG	primary command group	(10)	M	-	(PCG = ACG v	UCG v	LAG v	TAG)											
PPC	parallel poll configure	(10)	M	AC	X	Ø	Ø	Ø	Ø	Ø	1	Ø	1	XXX	X	X	X	X	X
PPE	parallel poll enable	(6,10)	M	SE	X	1	1	Ø	S	P	P	P	3	2	1	XXX	X	X	X
PPD	parallel poll disable	(7,10)	M	SE	X	1	1	1	D	D	D	D	4	3	2	1	XXX	X	X
PPR1	parallel poll response 1		U	ST	X	X	X	X	X	X	X	X	1	XXX	X	X	X	X	X
PPR2	parallel poll response 2		U	ST	X	X	X	X	X	X	X	1	X	XXX	X	X	X	X	X
PPR3	parallel poll response 3		U	ST	X	X	X	X	X	X	1	X	X	XXX	X	X	X	X	X
PPR4	parallel poll response 4		U	ST	X	X	X	X	1	X	X	X	XXX	X	X	X	X	X	X
PPR5	parallel poll response 5		U	ST	X	X	X	1	X	X	X	X	XXX	X	X	X	X	X	X
PPR6	parallel poll response 6		U	ST	X	X	1	X	X	X	X	X	XXX	X	X	X	X	X	X
PPR7	parallel poll response 7		U	ST	X	1	X	X	X	X	X	X	XXX	X	X	X	X	X	X
PPR8	parallel poll response 8		U	ST	1	X	X	X	X	X	X	X	XXX	X	X	X	X	X	X
PPU	parallel poll unconfigure	(10)	M	UC	X	Ø	Ø	1	Ø	1	Ø	1	XXX	X	X	X	X	X	X
REN	remote enable		U	UC	X	X	X	X	X	X	X	X	XXX	X	X	X	X	1	
RFD	ready for data		U	HS	X	X	X	X	X	X	X	X	XØ	X	X	X	X	X	X
RQS	request service	(9)	U	ST	X	1	X	X	X	X	X	X	XXX	X	X	X	X	X	X
SCG	secondary command group	(10)	M	SE	X	1	1	X	X	X	X	X	XXX	X	X	X	X	X	X
SDC	select device clear	(10)	M	AC	X	Ø	Ø	Ø	Ø	Ø	1	Ø	Ø	XXX	X	X	X	X	X
SPD	serial poll disable	(10)	M	UC	X	Ø	Ø	1	1	Ø	Ø	1	XXX	X	X	X	X	X	X
SPE	serial poll enable	(10)	M	UC	X	Ø	Ø	1	1	Ø	Ø	Ø	XXX	X	X	X	X	X	X

TABLE 2, Continued

		Bus signal line(s) and coding that asserts the true value of the message																					
MNEMONIC	MESSAGE NAME	T Y P E	C L S S	D A T A	8	7	6	5	4	3	2	1	NN										
													VDC	N	I	Q	C						
																		DRD	A	E	S	I	R
SRQ	service request	U	ST	X	X	X	X	X	X	X	X	X	XXX	X	X	1	X	X					
STB	status byte (8,9)	M	ST	S	X	S	S	S	S	S	S	S	XXX	X	X	X	X	X					
				8		6	5	4	3	2	1												
TCT	take control (10)	M	AC	X	Ø	Ø	Ø	Ø	1	Ø	Ø	1	XXX	X	X	X	X	X					
TAG	talk address group (10)	M	AD	X	1	Ø	X	X	X	X	X	X	XXX	X	X	X	X	X					
UCG	universal com- mand group (10)	M	UC	X	Ø	Ø	1	X	X	X	X	X	XXX	X	X	X	X	X					
NL	unlisten (10)	M	AD	X	Ø	1	1	1	1	1	1	1	XXX	X	X	X	X	X					
UNT	untalk (10)	M	AD	X	1	Ø	1	1	1	1	1	1	XXX	X	X	X	X	X					

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(SENT AND RECEIVED WITH ATN=1)

MULTILINE INTERFACE MESSAGES: ISO-7 BIT CODE REPRESENTATION

(SENT AND RECEIVED WITH ATN=1)

